

6 MHz Synchronous Rectification Buck-Boost DC/DC Converter IC

Description

The MB39C326 is a high efficiency, low noise synchronous, Buck-boost DC/DC converter designed for powering the radio frequency power amplifiers (RFPA) in 3G/GSM mobile handsets and other mobile applications.

Features

■ High efficiency
 Input voltage range
 ∴ 2.5 V to 5.5 V
 ■ Adjustable output voltage range
 ∴ 0.8 V to 5.0 V

■ Maximum output current (Buck, PWM mode) : 1200 mA (V_{IN} = 5.0 V to 5.5 V, at Vo=5.0 V)

: 1200 mA (V_{IN} = 3.6 V to 5.5 V, at Vo=3.6 V) : 1200 mA (V_{IN} = 3.3 V to 5.5 V, at Vo=3.3 V)

(Boost, PWM mode) : $900 \text{ mA} (V_{IN} = 3.7 \text{ V to } 5.0 \text{ V, at Vo} = 5.0 \text{ V})$

: 700 mA (V_{IN} = 2.5 V to 3.6 V, at Vo=3.6 V)

: 800 mA (V_{IN} = 2.5 V to 3.3 V, at V_{O} =3.3 V)

(Buck, Power save mode, $$:600\ mA\ (V_{IN}=5.0\ V\ to\ 5.5\ V,\ at\ Vo=5.0\ V)$$

ILIMSEL=H) : $600 \text{ mA} (V_{IN} = 3.6 \text{ V to } 5.5 \text{ V, at Vo=} 3.6 \text{ V})$

: 600 mA (V_{IN} = 3.3 V to 5.5 V, at Vo=3.3 V)

(Boost, Power save mode, $$:500\ mA\ (V_{IN}=3.7\ V\ to\ 5.0\ V,\ at\ Vo=5.0\ V)$$

ILIMSEL=H) : $400 \text{ mA} (V_{IN} = 2.5 \text{ V to } 3.6 \text{ V}, \text{ at Vo} = 3.6 \text{ V})$

: 500 mA (V_{IN} = 2.5 V to 3.3 V, at V_{O} = 3.3 V)

■ Quiescent current: 50 µA

■ 6 MHz PWM operation allows 0.5 µH small form inductor

■ Automatic Transition between Buck mode and boost mode

■ Power save Mode for improved efficiency at light load current

Selectable output voltage with external resistor

Built-in Over temperature protection circuit

■ Built-in Under voltage lockout protection circuit

■ Package: WL-CSP (20 pin 0.4 mm-ball-pitch 2.15 x 1.94 mm)

Applications

- Products that use 1-cell lithium batteries for the power supply
- RF power amplifier
- Cell-phone
- RF-PC card and PDA

Note: This product supports the web-based design simulation tool, Easy DesignSim. It can easily select external components and can display useful information. Please access from http://cypress.transim.com/login.aspx

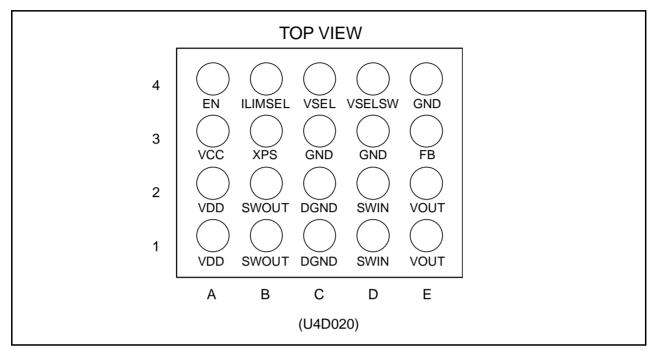


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1. Pin Assignments

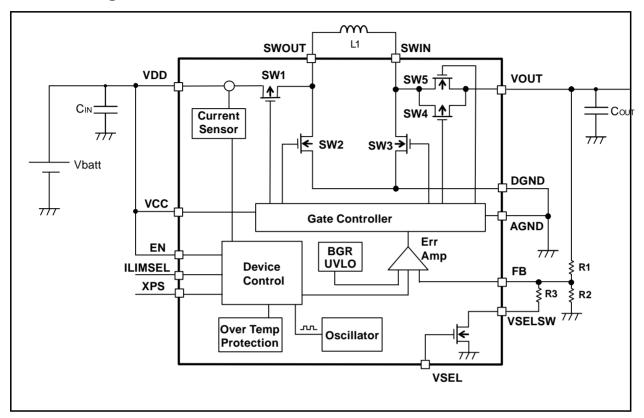


2. Pin Descriptions

Pin No.	Pin Name	I/O	Description
A4	EN	ı	IC Enable input pin (H: Enable, L: Shutdown)
E3	FB	ı	Voltage feedback pin
C3, D3, E4	GND	-	Control / Logic ground pins
B4	ILIMSEL	ı	Inductor peak current limit pin
B1, B2	SWOUT	ı	Connection pins for Inductor
D1, D2	SWIN	ı	Connection pins for Inductor
C1, C2	DGND	-	Power ground pins
C4	VSEL	ı	Output voltage select pin (H: Using R3 L: No using R3)
D4	VSELSW	-	Connection pin for output voltage setting resistor R3
A1, A2	VDD	ı	Electric power input pin for DCDC converter output voltage
A3	VCC	ı	Electric power input pin for IC control block
B3	XPS	I	Power save mode pin (H: PWM mode, L: Power save mode)
E1, E2	VOUT	0	Buck-boost converter output pins



3. Block Diagram



4. Function

(1) Gate Controller

It is controlled the synchronous rectification operation of built-in 2-P-ch MOS FETs and 2-N-ch MOS FETs according to frequency (6 MHz) set with a oscillator at the normal operation.

(2) Error Amp & phase compensation circuit

This compares the feedback voltage and the reference voltage (VREF). This IC contains the phase compensation circuit which optimizes the IC operation. Therefore, it is unnecessary to consideration of the phase compensation circuit, and external parts for the phase compensation.

(3) Band gap reference circuit

A high accuracy reference voltage is generated with BGR (band gap reference) circuit.

(4) Oscillator

The internal oscillator output a 6 MHz clock signal to set a switching frequency.

(5) Over temperature protection circuit

The over temperature protection circuit is built-in as a protection circuit. When junction temperature reaches +125 °C, the over temperature protection circuit turns off all N-ch MOS FETs and P-ch MOS FETs. Also, when the junction temperature falls to +110 °C, this IC operates normally.

(6) Inductor peak current limit circuit (Current Sensor + Device Control)

The inductor peak current limit circuit detects the current (I_{LX}) which flows from built-in P-ch MOS FET connected to VDD into an external inductor and limits the inductor peak current (I_{PK}).



(7) Power save mode operation

Power save mode is used to improve efficiency at the light load. By setting the XPS pin to "L" level, power save mode is set and the operation is performed in PWM mode or PFM mode depending on the load current. At this time, if the load current is low, this IC operates with PFM (PulseFrequency Modulation). It should be used above $V_{OUT} = 0.8$ V. If the output voltage becomes lower than the setting value at the light load, switching is performed several times and the output voltage rises. If the output voltage reaches the setting value, it changes to the stop state, all of the four FETs are turned off, and the switching loss and the dissipation power for the circuit are suppressed.

Consumption current in stop state at the power save mode becomes about 50 µA.

■ Function Table

Mode	XPS	VDC	VDC	VDC	VDC	VDC	VDC	ILIMSEL	Input Voltag	je Range[V]	Output Volt	age Range[V]	Inductor peak Current			
Wiode		ILIMSEL	Min	Max	Min	Max	Limit (I _{PK}) [A]									
PWM mode	Н	L					3.1									
Dower save mode	_	Н	2.5	2.5	2.5	2.5	2.5	2.5	2.5	2.5	2.5	2.5	2.5 5.5	0.8	5.0	1.3
Power save mode		L					0.49									

Note: Input of (XPS, ILIMSEL = H, H) is prohibited.

(8) EN pin

When the EN pin is set to "H" level, the device operation is enabled. When the EN pin is set to GND, the device is switched to shutdown mode.

When the EN pin is set to "L" level, the device is switched to shutdown mode.

In shutdown mode, the regulator stops switching, all FET switches are turned off, and the load is disconnected from the input.

(9) VSEL pin

MB39C326 has a function to change the output voltage with the VSEL pin and additional resistance.

For details of the output voltage settings, see the section 2. of "Programming the Output Voltage" in 9. Application .

(10) Buck-Boost operations

MB39C326 operates in Buck or Boost mode by monitoring the VCC/VOUT voltage with a newly developed PWM controller. The transition between buck and boost mode is smooth and the efficiency is high.

During Buck mode (VCC > VOUT), SW1 and SW2 perform switching while SW3 is fixed to OFF and SW4 and 5 are fixed to ON. During Boost mode (VCC < VOUT), SW3, SW4 and SW5 perform switching while SW1 is fixed to ON and SW2 is fixed to OFF.

The voltage values of VCC and VDD at the switching between buck and boost vary depending on the load current, the environmental temperature and the process variations.

(11) Startup circuit

MB39C326 has the soft-start function to prevent rush current upon turning on of the power.

The startup time is approximately 100 µs.



5. Absolute Maximum Ratings

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Parameter	Symbol	Condition	Min	Max	Unit
Power supply voltage	V_{MAX}	VDD, VCC	-0.3	+7.0	V
Signal input voltage	V _{INMAX}	EN, XPS, VSEL, ILIMSEL	-0.3	V _{DD} + 0.3	V
Power dissipation	P_D	Ta ≤ +25°C	-	1080	mW
Storage temperature	T _{STG}	-	-65	+150	°C
	V_{ESDH}	Human Body Model (100 pF, 1.5 kΩ)	-2000	+2000	V
ESD Voltage	V_{ESDM}	Machine Model (200 pF, 0Ω)	-200	+200	V
	V _{ESDC}	Charged device model	-1000	+1000	V
Maximum junction temperature	Tj- _{MAX}	-	-	+95	°C

WARNING:

Semiconductor devices may be permanently damaged by application of stress (including, without limitation, voltage, current or temperature) in excess of absolute maximum ratings. Do not exceed any of these ratings.

6. Recommended Operating Conditions

_				Value			
Parameter	Symbol	Condition	Min	Тур	Max	Unit	
Power supply voltage	V_{DD}	VDD, VCC	2.5(*1)	3.7	5.5(*1)	V	
Signal input voltage	V_{IDD}	EN, XPS, VSEL, ILIMSEL	0.0	-	VDD	V	
	lo (Max1)	V _{IN} = 5.5, Vo = 5.0V, XPS = H, ILIMSEL = L	-	-	1200	mA	
	lo (Max2)	V _{IN} = 5.5, Vo = 4.4V, XPS = H, ILIMSEL = L	-	-	1200	mA	
	lo (Max3)	V_{IN} = 5.5, Vo = 3.6 V , XPS = H , $ILIMSEL$ = L	-	-	1200	mA	
	io (iviaxs)	V _{IN} = 4.2, Vo = 3.6V, XPS = H, ILIMSEL = L	-	-	1200	mA	
	lo (Mov4)	V_{IN} = 5.5, Vo = 3.3 V , XPS = H , $ILIMSEL$ = L	-	-	1200	mA	
	lo (Max4)	V_{IN} = 3.7, Vo = 3.3 V , XPS = H , $ILIMSEL$ = L	-	-	1200	mA	
Output current (Buck)	lo (Max5)	V _{IN} = 5.5, Vo = 2.0V, XPS = H, ILIMSEL = L	-	-	1200	mA	
PWM mode		V_{IN} = 3.7, Vo = 2.0 V , XPS = H , $ILIMSEL$ = L	-	-	1200	mA	
FVVIVITIOUE		V_{IN} = 2.5, Vo =2 .0V, XPS = H, ILIMSEL = L	-	-	1200	mA	
	Io (Max6)	V_{IN} = 5.5, Vo = 1.2 V , XPS = H , $ILIMSEL$ = L	-	-	700	mA	
		V_{IN} = 3.7, Vo = 1.2 V , XPS = H , $ILIMSEL$ = L	-	-	600	mA	
		V_{IN} = 2.5, Vo = 1.2 V , XPS = H , $ILIMSEL$ = L	-	-	600	mA	
		V_{IN} = 5.5, Vo = 0.8V, XPS = H, ILIMSEL = L	-	-	600	mA	
		V _{IN} = 3.7, Vo = 0.8V, XPS = H, ILIMSEL = L	-	-	500	mA	
		V _{IN} = 2.5, Vo = 0.8V, XPS = H, ILIMSEL = L	-	-	250	mA	
	lo (Max8)	V _{IN} = 2.5V, Vo = 3.3V, XPS = H, ILIMSEL = L	-	-	800	mA	
	lo (Max9)	V _{IN} = 2.5V, Vo = 3.6V, XPS = H, ILIMSEL = L	-	-	700	mA	
Output current (Boost)	lo (Mov40)	V _{IN} = 3.7V, Vo = 4.4V, XPS = H, ILIMSEL = L	-	-	1000	mA	
PWM mode	lo (Max10)	V _{IN} = 2.5V, Vo = 4.4V, XPS = H, ILIMSEL = L	-	-	700	mA	
	lo (Moy11)	V _{IN} = 3.7V, Vo = 5V, XPS = H, ILIMSEL = L	-	-	900	mA	
	lo (Max11)	V _{IN} = 2.5V, Vo = 5V, XPS = H, ILIMSEL = L	-	=	600	mA	



_				Value		
Parameter	Symbol	Condition	Min	Тур	Max	Unit
	lo (Max12)	V _{IN} = 5.5, Vo = 5.0V, XPS = L, ILIMSEL = H	-	-	600	mA
	lo (Max13)	V _{IN} = 5.5, Vo = 4.4V, XPS = L, ILIMSEL = H	-	-	600	mA
	la (May14)	V _{IN} = 5.5, Vo = 3.6V, XPS = L, ILIMSEL = H	=	-	600	mA
	lo (Max14)	V_{IN} = 4.2, Vo = 3.6 V , XPS = L , $ILIMSEL$ = H	=	-	600	mA
	la (May4E)	V _{IN} = 5.5, Vo = 3.3V, XPS = L, ILIMSEL = H	=	-	600	mA
	lo (Max15)	V_{IN} = 3.7, Vo = 3.3 V , XPS = L , $ILIMSEL$ = H	-	-	600	mA
Output current (Buck)		V _{IN} = 5.5, Vo = 2.0V, XPS = L, ILIMSEL = H	-	-	600	mA
Power save mode,	lo (Max16)	V _{IN} = 3.7, Vo = 2.0V, XPS = L, ILIMSEL = H	-	-	500	mA
ILIMSEL=H		V _{IN} = 2.5, Vo = 2.0V, XPS = L, ILIMSEL = H	-	-	500	mA
		V _{IN} = 5.5, Vo = 1.2V, XPS = L, ILIMSEL = H	-	-	400	mA
	lo (Max17)	V _{IN} = 3.7, Vo = 1.2V, XPS = L, ILIMSEL = H	-	-	300	mA
		V _{IN} = 2.5, Vo = 1.2V, XPS = L, ILIMSEL = H	=	-	300	mA
	lo (Max18)	V _{IN} = 5.5, Vo = 0.8V, XPS = L, ILIMSEL = H	-	-	400	mA
		V _{IN} = 3.7, Vo = 0.8V, XPS = L, ILIMSEL = H	=	-	200	mA
		V _{IN} = 2.5, Vo = 0.8V, XPS = L, ILIMSEL = H	=	-	200	mA
	lo (Max19)	V _{IN} = 2.5V, Vo = 3.3V, XPS = L, ILIMSEL = H	=	-	500	mA
Outrout augment (Decet)	lo (Max20)	V _{IN} = 2.5V, Vo = 3.6V, XPS = L, ILIMSEL = H	=	-	400	mA
Output current (Boost) Power save mode,	lo (Mov21)	V_{IN} = 3.7V, Vo = 4.4V, XPS = L, ILIMSEL = H	=	-	600	mA
ILIMSEL=H	lo (Max21)	V _{IN} = 2.5V, Vo = 4.4V, XPS = L, ILIMSEL = H	=	-	350	mA
ILIIVISEL=II	lo (Mov22)	$V_{IN} = 3.7V$, $Vo = 5V$, $XPS = L$, $ILIMSEL = H$	=	-	500	mA
	lo (Max22)	V _{IN} = 2.5V, Vo = 5V, XPS = L, ILIMSEL = H	=	-	300	mA
Output current (Buck) Power save mode, ILIMSEL=L	lo (Max23)	V _{IN} = 3.7, Vo = 3.3V, XPS = L, ILIMSEL = L	-	-	160	mA
Output current (Boost) Power save mode, ILIMSEL=L	lo (Max24)	V _{IN} = 2.5, Vo = 5V, XPS = L, ILIMSEL = L	-	-	60	mA
Operating Ambient temperature	Та	-	-40	-	+85	°C
Junction temperature range	Tj	-	-40	-	+95	°C
Inductor value	L	-	-	0.5	-	μH
Feedback resistor value	R1	-	-	620	-	kΩ

^{*1:} Depending on the setting condition. See "■ Function Table" in "4. Function (7) Power save mode operation".

WARNING:

- 1. The recommended operating conditions are required in order to ensure the normal operation of the semiconductor device. All of the device's electrical characteristics are warranted when the device is operated under these conditions.
- 2. Any use of semiconductor devices will be under their recommended operating condition.
- 3. Operation under any conditions other than these conditions may adversely affect reliability of device and could result in device failure.
- 4. No warranty is made with respect to any use, operating conditions or combinations not represented on this data sheet. If you are considering application under any conditions other than listed herein, please contact sales representatives beforehand.



7. Electrical Characteristics

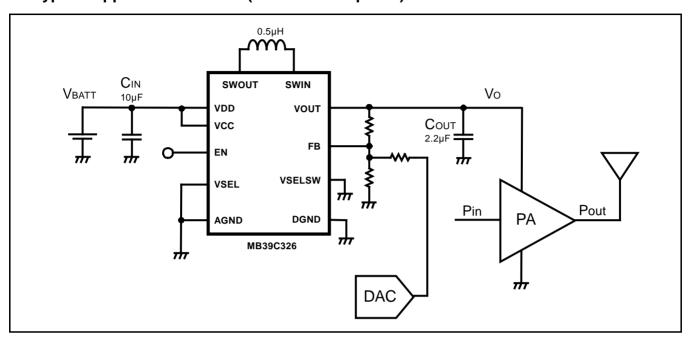
The specifications apply under the recommended operating condition.

Parameter		0	O and distant		11-11		
		Symbol Condition		Min	Тур	Max	Unit
Output voltage range		Vo	-	0.8	-	5.0	V
Feedback voltage	ge	V_{FB}	-	490	500	510	mV
Line Regulation		V _{LINE}	IO = 0 to 800 mA	-	0.2	-	%
Load Regulation	า	V_{LOAD}	IO = 0 to 800 mA	-	0.3	-	%
			XPS = H, ILIMSEL = L	2.50	3.10	3.75	А
Inductor peak c	urrent limit	I _{PK}	XPS = L, ILIMSEL = H	1.05	1.30	1.60	Α
			XPS = L, ILIMSEL = L	0.36	0.49	0.60	А
Oscillation frequ	iency	fosc	-	5.2	5.8	6.4	MHz
Shutdown curre	nt	I _{SD}	EN = L	-	-	2	μA
Quiescent current		IQ	EN = H, XPS = L, $V_{IN} = 3.7V, V_O = 3.3V,$ $I_O = 0 \text{ mA}$	-	50	-	μА
	SW1		V _{DD} = 3.7V, V _O = 3.3V, Ta = +25°C	-	63.5	84	mΩ
	SW2			-	124	175	
SW FET ON resistance	SW3	Rdson		-	82	116	
resistance	SW4	1		-	123	164	
	SW5			-	51	72	1
0		T _{OTPH}	-	-	135(*1)	-	°C
Over temperature protection		T _{OTPL}	-	-	110(*1)	-	°C
UVLO		V _{UVLOH}	-	1.9	2.0	2.1	V
Threshold voltage		V _{UVLOL}	-	1.8	1.9	2.0	V
Cianal innut the			EN, XPS, VSEL, ILIMSEL	0.0	-	0.25	V
Signal input thre	esnoia voitage	V _{IH}	EN, XPS, VSEL, ILIMSEL	1.5	-	VDD	V
Signal input cur	rent	I _{CTL}	EN, XPS, VSEL, ILIMSEL	-	-	0.1	μA

^{*1:} This parameter is not be specified. This should be used as a reference to support designing the circuits.



8. Typical Applications Circuit (RF Power Amplifier)





9. Application Notes

Programming the Output Voltage

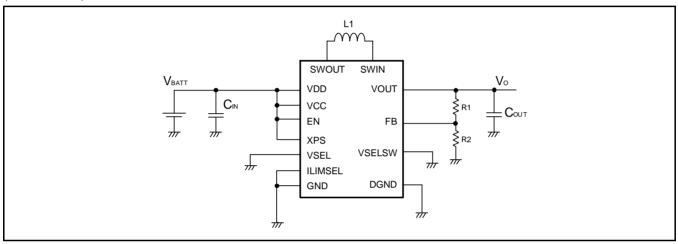
Output voltage is calculated using the equation (1) below.

Use R1 resistor value of 620 kΩ. Built-in phase compensation circuit is generated according to this resistor value.

1. Not using a selectable voltage option

$$V_O = V_{FB} \times \frac{R_1 + R_2}{R_2}$$

 $(V_{FB} = 500 \text{ mV})$



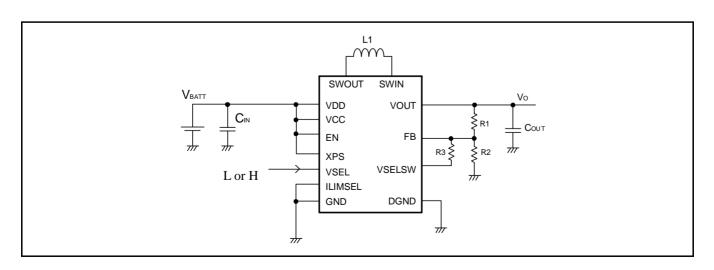
2. Using a selectable voltage option

When VSEL = L

$$V_O = V_{FB} \mathbf{x} \qquad \frac{R_1 + R_2}{R_2}$$

When VSEL = H

$$V_O = V_{FB} \times \frac{R_1 + (R_2//R_3)}{R_2//R_3}$$

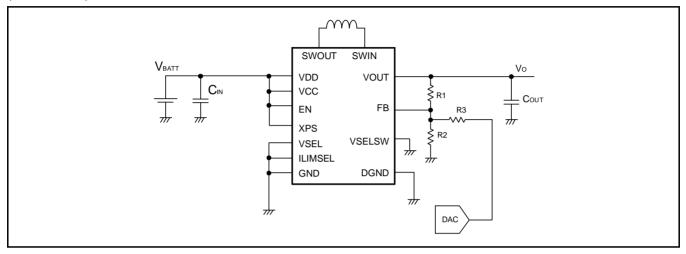




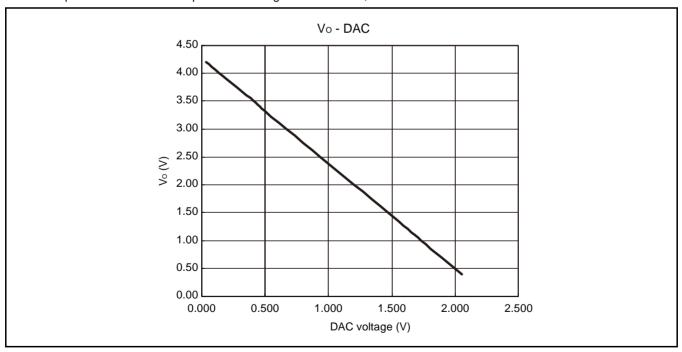
3. When the output variable is dynamically performed

$$V_{O} = -\frac{R_{1}}{R_{3}} \times V_{DAC} + V_{FB} \times \frac{R_{1}}{R_{3}} + \frac{R_{1}}{R_{2}} + 1)$$

 $(V_{FB} = 500 \text{ mV})$



Relationship between DAC and output when setting to R1 = 620 k Ω , R2 = 110 k Ω and R3 = 330 k Ω





10. Inductor Selection

The recommended inductor is $0.5 \mu H (0.47 \mu H)$.

To acquire a high-efficiency, select an inductor with low ESR.

Confirm in use conditions that the coil current does not exceed the rated saturation current.

It is recommended that the switch current limit value is considered.

Note that the permissible current value might be low about some products with high ESR because of the device temperature increasing.

The following table shows the recommended inductor.

Vendor	Part #		Size	DCR[Ω]	Isat[A]	
vendor	Part#	L[mm]	W[mm]	H[mm]	(max)	(-30%)
Coilcraft	XPL2010-501ML	1.9	2.0	1.0	0.045	2.64
ALPS	GLCHKR4701A	2.0	1.6	1.0	0.035	3.6

Coilcraft : Coilcraft, Inc.

ALPS: Alps Green Devices Co., Ltd

11. Input Capacitor Selection

It is recommended to place a low ESR ceramic bypass capacitor at least 10 µF close to VDD and GND because the input capacitor is the power-supply voltage.

The execution capacity of some ceramic capacitors greatly decreases when adding bias.

Select a product by checking the part characteristics of manufacturer because small size parts or low voltage rating parts tend to have that characteristic.

12. Output Capacitor Selection

The recommended standard capacity of the output capacitor is 2.2 µF in PWM mode.

When using in power save mode, the capacitor with larger capacity (around 22 μ F) is recommended to reduce the ripple voltage at PFM operation.

To suppress the decrease of output voltage during the load change, adjust with a larger capacitor.

Larger capacitors and low ESR capacitors is useful to reduce the ripple.

13. Thermal Information

Power dissipation is 1080 mW Max.

Thermal resistance(θja) is 65°C /W (JEDEC). This value can be used to calculate the chip temperature.

Thermal resistance is calculated based on the usage of JEDEC standard boards. It is recommended to consider for the thermal design that the value may vary depending on the area of the board and the positions of the vias.

See "Power dissipation vs. Operation ambient temperature" in "15. Example of Standard Operation ".



14. Notes on Board Layout

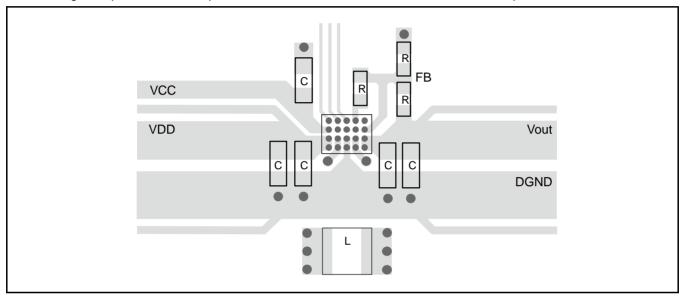
A suitable board layout is required for stable operations of this IC.

Place the peripheral component, input capacitance C_{IN} and the output capacitance C_{OUT} close to this IC as much as possible, and connect them with the shortest routes.

The routes with large current, in particular, the routes with variable current must be placed on the front surface with the shortest routes.

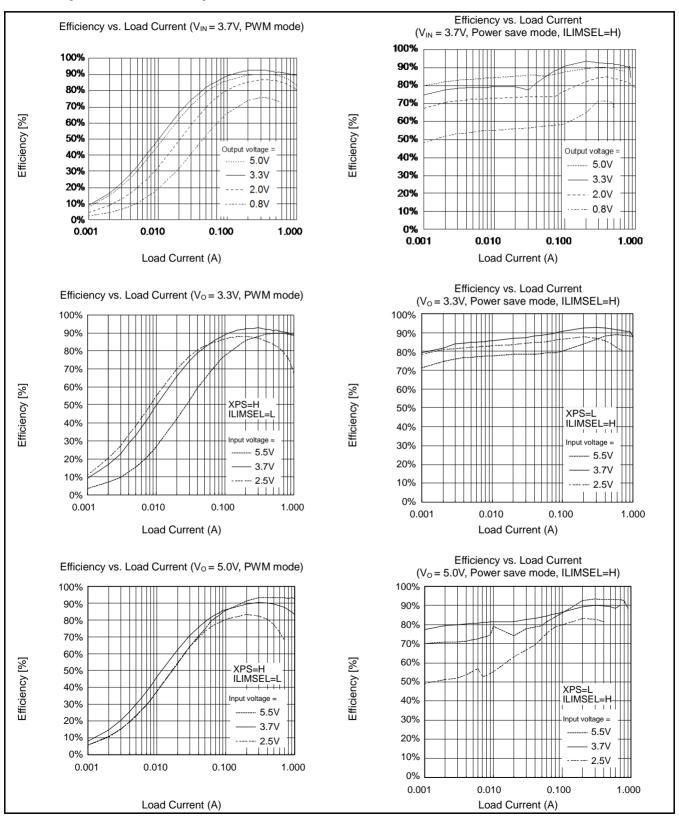
Separate DGND from GND and connect GND at one point close to C_{OUT}.

Provide the ground plane as much as possible on the IC mounted face. It is useful for heat dissipation.

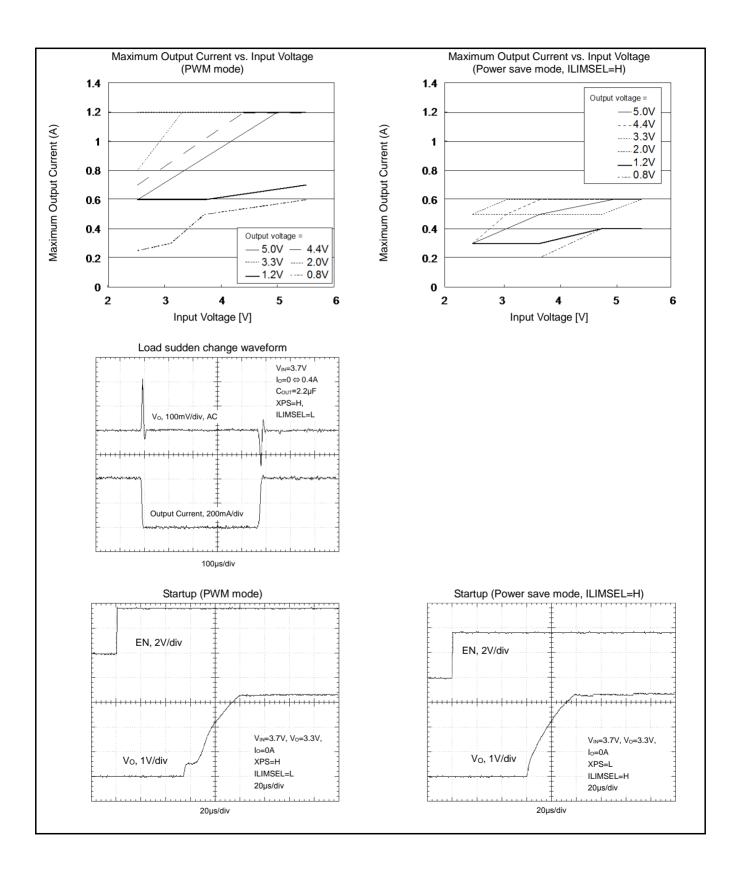




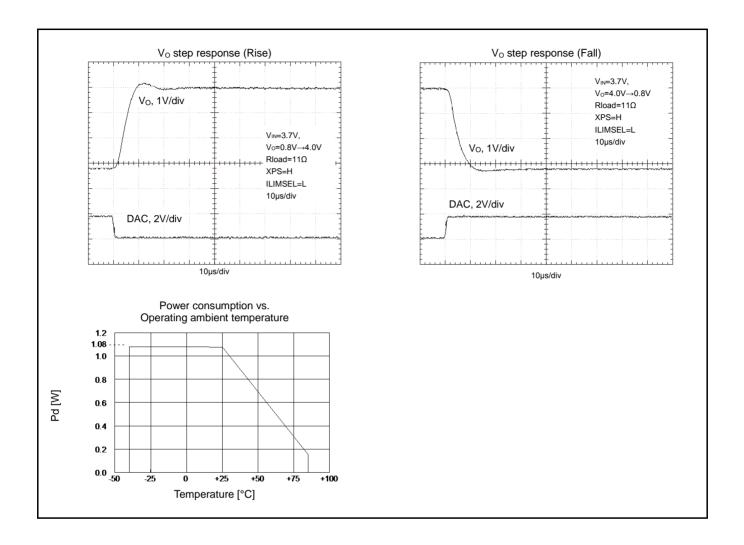
15. Example of Standard Operation Characteristics













16. Usage Precaution

■ Do not configure the IC over the maximum ratings.

If the IC is used over the maximum ratings, the LSI may be permanently damaged.

It is preferable for the device to be normally operated within the recommended usage conditions. Usage outside of these conditions can have a bad effect on the reliability of the LSI.

■ Use the devices within recommended operating conditions.

The recommended operating conditions are the recommended values that guarantee the normal operations of LSI.

The electrical ratings are guaranteed when the device is used within the recommended operating conditions and under the conditions stated for each item.

- Printed circuit board ground lines should be set up with consideration for common impedance.
- Take appropriate measures against static electricity.
- Containers for semiconductor materials should have anti-static protection or be made of conductive material.
- After mounting, printed circuit boards should be stored and shipped in conductive bags or containers.
- □ Work platforms, tools, and instruments should be properly grounded.
- Working personnel should be grounded with resistance of 250 k Ω to 1 M Ω in series between body and ground.
- Do not apply negative voltages.

The use of negative voltages below -0.3V may cause the parasitic transistor to be activated on LSI lines, which can cause malfunctions.

17. Notes on Mounting

In general, the underfill material and sealing method affect the reliability of mounting.

Cypress does not evaluate the mounting using the underfill material.

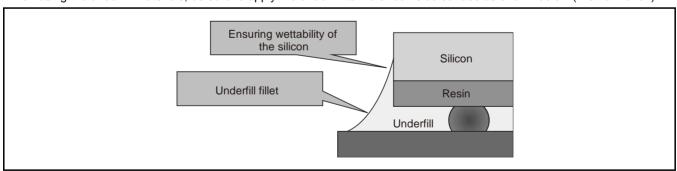
It is advisable for each customer to evaluate the mounting enough.

WL-CSP has a surface boundary between silicon and resin at the side of the package.

Resin may be pulled by the board because of the underfill material and its shape and the state, and stress may occur at the surface boundary.

The result may vary depending on the board and the underfill material used by each customer; therefore, it is advisable for each customer to evaluate the mounting enough in order to apply to the products.

When using the underfill materials, be sure to apply the underfill to the silicon side surface as shown below (fillet formation).





18. Ordering Information

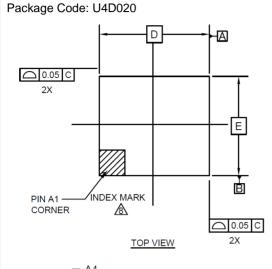
Part Number	Package	Remarks
MP30C336DW	20-pin plastic WL-CSP	
MB39C326PW	(U4D020)	_

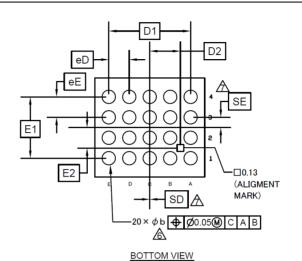
19. RoHS Compliance Information

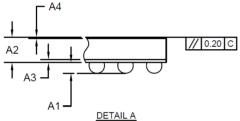
The LSI products of Cypress with "E1" are compliant with RoHS Directive, and has observed the standard of lead, cadmium, mercury, Hexavalent chromium, polybrominated biphenyls (PBB), and polybrominated diphenyl ethers (PBDE). A product whose part number has trailing characters "E1" is RoHS compliant.

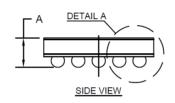


20. Package Dimensions









SYMBOL	DI	DIMENSIONS			
STIMBOL	MIN.	NOM.	MAX.		
Α	_	_	0.625		
A1	0.207	0.21	0.213		
A2	0	.365 BS	С		
A3	(0.05 BSC			
A4	0	.025 BS	С		
D	2.15 BSC				
Е	1.94 BSC				
D1		1.60 BSC			
E 1		1.20 BSC			
D2	(0.60 BSC)		
E 2	(0.40 BSC	>		
MD		5			
ME		4			
n	20				
φb	0.23 0.26 0.29				
eD	0.40 BSC				
eE	0.40 BSC				
SD/SE	0	0 / 0.20 BSC			

NOTES

- 1. ALL DIMENSIONS ARE IN MILLIMETERS.
- 2. DIMENSIONS AND TOLERANCES METHODS PER ASME Y14.5-2009. THIS OUTLINE CONFORMS TO JEP95, SECTION 4.5.
- 3. BALL POSITION DESIGNATION PER JEP95, SECTION 3, SPP-010.
- 4. "e" REPRESENTS THE SOLDER BALL GRID PITCH.
- 5. SYMBOL "MD" IS THE BALL MATRIX SIZE IN THE "D" DIRECTION. SYMBOL "ME" IS THE BALL MATRIX SIZE IN THE "E" DIRECTION. IN IS THE NUMBER OF POPULATED SOLDER BALL POSITIONS FOR MATRIX SIZE MD X ME.
- ⚠ DIMENSION "b" IS MEASURED AT THE MAXIMUM BALL DIAMETER IN A PLANE PARALLEL TO DATUM C.
- M "SD" AND "SE" ARE MEASURED WITH RESPECT TO DATUMS A AND B AND DEFINE THE POSITION OF THE CENTER SOLDER BALL IN THE OUTER ROW. WHEN THERE IS AN ODD NUMBER OF SOLDER BALLS IN THE OUTER ROW "SD" OR "SE" = 0.
 - WHEN THERE IS AN EVEN NUMBER OF SOLDER BALLS IN THE OUTER ROW, "SD" = eD/2 AND "SE" = eE/2.
- ⚠A1 CORNER TO BE IDENTIFIED BY CHAMFER, LASER OR INK MARK. METALLIZED MARK INDENTATION OR OTHER MEANS.
- 9. "+" INDICATES THE THEORETICAL CENTER OF DEPOPULATED BALLS.
- 10. JEDEC SPECIFICATION NO. REF: N/A.

002-16171 Rev. **



21. Major Changes

Spansion Publication Number: MB39C326_ DS405-00001

Page	Section	Change Results					
Revision 1.0	Revision 1.0						
-	-	Initial release					

NOTE: Please see "Document History" about later revised information.



Document History

Document Title: MB39C326 6MHz Synchronous Rectification Buck-Boost DC/DC Converter IC

Document Number: 002-08348

Revision	ECN	Orig. of Change	Submission Date	Description of Change
**	1	TAOA	01/31/2014	Migrated to Cypress and assigned document number 002-08348. No change to document contents or format.
*A	5131396	TAOA	02/10/2016	Updated to Cypress template
*B	5732493	ніхт	05/11/2017	Updated Pin Assignments: Added the package name, U4D020 Updated Ordering Information: Change the package name from WLP-20P-M01 to U4D020 Deleted "EV Board Ordering Information" Deleted "Marking" Deleted "Labeling Sample" Deleted "MB39C326PW Recommended Conditions of Moisture Sensitivity Level" Updated Package Dimensions: Updated to Cypress format



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